

Contents

| | |
|---|-----------|
| 1. Introduction | 13 |
| 1.1. Thin films — an overview | 13 |
| 1.2. The aim and scope of the monograph | 16 |
| 1.3. Thin films deposition methods | 19 |
| 1.3.1. Physical vapour deposition | 19 |
| 1.3.2. Chemical vapour deposition | 20 |
| 1.3.3. Thermal spray deposition | 21 |
| 1.4. Failure modes in thin films | 22 |
| 1.5. Thermal barrier coating system | 25 |
| 1.5.1. Substrate alloy | 27 |
| 1.5.2. Bond coat | 28 |
| 1.5.3. Thermal barrier coatings | 30 |
| 1.5.4. Degradation of APS TBC systems | 33 |
| 1.5.5. Modelling of TBC systems | 35 |
| 1.6. Human skin | 38 |
| 1.6.1. Structure of human skin | 38 |
| 1.6.2. Mechanical properties of human skin | 39 |
| 1.6.3. Skin imaging | 41 |
| 2. Preliminaries | 45 |
| 2.1. Fracture mechanics of interface cracks | 45 |
| 2.1.1. General case $\epsilon \neq 0$ | 47 |
| 2.1.2. Special case $\epsilon = 0$ | 49 |
| 2.1.3. Energy release rate | 50 |
| 2.2. Cohesive zone model | 51 |
| 2.2.1. General formulation | 52 |
| 2.2.2. Specification to a slip response | 56 |

| | |
|--|------------|
| 3. An energy model of segmentation cracking of thin films | 59 |
| 3.1. Introduction | 59 |
| 3.2. Problem formulation | 60 |
| 3.3. Residual stresses | 63 |
| 3.4. External loading | 65 |
| 3.4.1. Stage I | 67 |
| 3.4.2. Stage II | 69 |
| 3.5. Energy model | 71 |
| 3.5.1. Failure model based on the total system energy | 72 |
| 3.5.2. Failure model based on the film/interface sub-system energy | 79 |
| 3.6. Specification of the fracture energy of a silicon oxide thin coating | 80 |
| 3.7. The energy model and stress redistribution models | 88 |
| 3.8. Conclusions | 90 |
| 4. Modelling of thermal barrier coatings | 93 |
| 4.1. Introduction | 93 |
| 4.2. Through-thickness cracking cracking | 94 |
| 4.2.1. Experimental setup | 94 |
| 4.2.2. Experimental results | 96 |
| 4.2.3. Finite element model | 99 |
| 4.2.4. Mesh dependence | 105 |
| 4.2.5. Comparison with experimental results | 106 |
| 4.2.6. Effect of TBC critical energy release rate G_I on segmentation cracking | 108 |
| 4.3. Delamination | 109 |
| 4.3.1. The numerical model | 110 |
| 4.3.2. The time dependent behaviour of CMSX-4 | 115 |
| 4.3.3. Modelling of crack development | 116 |
| 4.3.4. Stress distribution without microcracks in the unit cell | 117 |
| 4.3.4.1. The influence of the time-dependent behaviour of CMSX-4 | 117 |
| 4.3.4.2. The effect of cyclic loading | 120 |
| 4.3.5. Crack development at the TGO/BC interface | 126 |
| 4.4. Conclusions | 131 |
| 5. Frictional delamination | 135 |
| 5.1. Introduction | 135 |
| 5.2. Problem formulation | 136 |
| 5.3. Dimensional analysis | 140 |
| 5.4. Observations - one dimensional slip model | 142 |
| 5.5. Superposition of solution | 145 |
| 5.6. Moving boundary $\partial\Omega$ | 148 |
| 5.7. Approximate solution | 151 |
| 5.8. Results | 154 |
| 5.8.1. Special case: $\nu = -1$ | 154 |

| | |
|---|------------|
| 5.8.2. Loading force P versus parameter l_0 | 156 |
| 5.8.3. Stress field | 158 |
| 5.8.4. Comparison with finite element results | 158 |
| 5.9. Conclusions | 161 |
| 6. Characterization of thin tissues via surface-wave sensing | 165 |
| 6.1. Introduction | 165 |
| 6.2. Conceptual sensor setup | 166 |
| 6.3. Point versus integral motion sensing | 168 |
| 6.4. Forward analysis | 169 |
| 6.4.1. Layered tissue model | 169 |
| 6.4.2. Sensing array | 170 |
| 6.4.3. Response of the substrate | 170 |
| 6.4.4. Response of the fiber | 172 |
| 6.4.5. Fiber-substrate interaction | 174 |
| 6.4.6. Solution method | 174 |
| 6.4.7. Computation of output voltages | 176 |
| 6.4.8. Comparison with finite element simulations | 177 |
| 6.4.9. Dominant modes of sensors' deformation | 177 |
| 6.5. Back-analysis | 182 |
| 6.5.1. Observations | 182 |
| 6.5.2. Minimization | 183 |
| 6.6. Numerical results | 184 |
| 6.6.1. Effect of number of sensors | 185 |
| 6.6.2. Effect of frequency sweep | 185 |
| 6.6.3. Experimental noise | 188 |
| 6.7. Conclusions | 191 |
| 7. Summary | 193 |
| A. Green's function for a one dimensional elastic strip | 199 |
| B. Green's functions for an infinite plate loaded by an in-plane point force | 201 |
| C. Parameters used in equations (6.4) | 209 |
| Bibliography | 211 |
| Extended summary in Polish | 229 |