

Contents

1. Introduction	13
1.1 The inverse problem of load identification	13
1.2 Structural health monitoring and load identification	15
1.3 Numerical models and experimental setups	17
1.4 Scope of the work	18
2. Load identification in linear structures	23
2.1 Introduction	23
2.1.1 Overview of the problem	23
2.1.2 State-of-the-art	24
2.1.3 Aims and techniques	27
2.2 Problem formulation	29
2.2.1 Impulse response matrices	29
2.2.2 Direct problem	33
2.2.3 Inverse problem	36
2.2.4 Practical considerations	37
2.3 Overdetermined case	42
2.4 Underdetermined case	46
2.4.1 Decomposition of excitation	47
2.4.2 Single-stage identification	52
2.5 Optimum sensor placement	53
2.5.1 Criterion of conditioning	55
2.5.2 Criterion of informativity	55
2.5.3 Compound criterion	56
2.6 Numerical example	56
2.6.1 The structure	56
2.6.2 Optimum placement of sensors	57
2.6.3 Actual excitation	61
2.6.4 Identification results	61

3. Virtual distortion method	67
3.1 Introduction	68
3.1.1 Structural reanalysis	68
3.1.2 Overview of the VDM	69
3.1.3 Introductory examples	72
3.1.4 VDM and load identification	75
3.2 Distortions of a finite element	76
3.2.1 Basis distortions and equivalent element loads	76
3.2.2 Total distortions	77
3.2.3 Decomposition of global elastic forces	78
3.2.4 Equation of motion of the original structure	78
3.3 Direct problem	79
3.3.1 Structural modifications and damages	79
3.3.2 Pseudo loads and virtual distortions	80
3.3.3 Solution scheme	82
3.3.4 Time discretization	83
3.4 Inverse problem	84
3.4.1 Objective function	85
3.4.2 Sensitivity analysis	86
3.4.3 Time discretization	89
4. Model-free structural health monitoring	93
4.1 State-of-the-art and introduction	94
4.2 Time-domain formulation	96
4.2.1 The direct problem	96
4.2.2 The inverse problem	102
4.2.3 Time discretization and numerical solution	106
4.3 Frequency-domain formulation	111
4.3.1 The direct problem	112
4.3.2 The inverse problem	113
4.3.3 FFT and windowing function	114
4.4 Identification of inelastic impacts	114
4.4.1 The direct problem	115
4.4.2 The inverse problem	115
4.5 Selected experimental results	116
4.5.1 The structure	116
4.5.2 Excitations and measurements	116
4.5.3 Single nodal mass modification	118
4.5.4 Modification of two nodal masses	120

5. Virtual isolation of substructures for local health monitoring	125
5.1 Motivation	126
5.2 State-of-the-art	127
5.2.1 Static case	127
5.2.2 Dynamic case	127
5.2.3 Substructure separation methods	129
5.3 Overview of the isolation method	129
5.3.1 Two-stage monitoring	129
5.3.2 Excitations, sensors and measured responses	130
5.3.3 Stage I: substructure isolation	133
5.3.4 Stage II: local identification	134
5.3.5 Substructure isolation and load identification	135
5.4 Isolation in time domain	135
5.4.1 Isolation with other types of virtual supports	137
5.4.2 Time discretization and numerical stability	139
5.5 Isolation in frequency domain	140
5.5.1 Isolation in time domain vs. isolation in frequency domain	141
5.5.2 FFT of the time-domain responses	142
5.6 Numerical examples	142
5.6.1 2-DOF mass-spring system	143
5.6.2 6-DOF mass-spring system	144
5.7 Experimental verification	152
5.7.1 Experimental setup	152
5.7.2 Isolation and identification in time domain	157
5.7.3 Isolation and identification in frequency domain	160
6. Simultaneous identification of damages and dynamic excitations	165
6.1 State-of-the-art	166
6.2 Damage-equivalent excitations	168
6.2.1 VDM-based formulation and the direct problem	168
6.2.2 Off-line identification	171
6.2.3 Online identification	174
6.2.4 Numerical example	175
6.2.5 Experimental example	184
6.3 Parametrization of loads	190
6.3.1 Modeling of moving masses	191
6.3.2 Coupled modeling of moving masses and damages	194
6.3.3 Identification	197
6.3.4 Numerical example	200

7. Load identification in elastoplastic structures	211
7.1 Bilinear isotropic hardening plasticity	213
7.2 The direct problem	214
7.2.1 Continuous formulation	214
7.2.2 Discrete-time setting	216
7.3 The inverse problem	221
7.3.1 Objective function	222
7.3.2 First order sensitivity analysis	222
7.3.3 Approximate second order sensitivity analysis	224
7.4 Numerical example	225
7.4.1 The structure	225
7.4.2 Actual excitation and the response	225
7.4.3 Sensor placement	227
7.4.4 Identification results	227
8. Conclusions	231
8.1 Original results	231
8.2 Further research	233
A. Linear inverse problem	235
A.1 Linear operators	235
A.1.1 Boundedness, continuity and compactness	236
A.1.2 Ill-posedness, ill-conditioning and regularization	237
A.2 Infinite dimensional integral problems	239
A.2.1 Linear integral operator	240
A.2.2 Linear integral equations	241
A.2.3 Discretization	246
A.3 Finite dimensional discretized problems	249
A.3.1 Solvability and conditioning	249
A.3.2 Numerical regularization	252
Bibliography	257